Dual methods for functions with bounded variation

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Joint work with A.Gasnikov (MIPT, Moscow)

Outline

- **1** Problem formulation
- **2** Bounds on the dual solution
- **3** Problems with bounded variation
- 4 Modified Gradient Methods
- 5 Fast Gradient Method
- 6 Examples

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Approximate solution: find $\bar{x} \in Q$ such that

$$f(\bar{x}) - f^* \le \epsilon_f, \quad ||A\bar{x} - b|| \le \epsilon_g.$$

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Assume for a moment that all norms are Euclidean.

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Standard subgradient method ensures

$$O\left(\left[\frac{L}{\epsilon_f} + \frac{\|A\|}{\epsilon_g}\right]^2 \operatorname{diam}^2 Q\right)$$
 iterations.

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• Optimal solution does not exist. Rate of convergence of the standard dual GMs = ?

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Bounding the dual solution

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Restricting ourselves to $x \in B(\bar{x}, \rho)$, we obtain

$$\rho \|\nabla f(x^*) - A^T y^*\|_* \le \langle \nabla f(x^*), \bar{x} - x^* \rangle \le \|\nabla f(x^*)\|_* \cdot D.$$

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Problems with bounded variation

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Assume that problem (\mathcal{P}) is solvable.

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We study numerical schemes for maximizing dual functions satisfying assumption (2).

Termination criterion

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Range of accuracy for the norm of the gradient

$$\epsilon_g^2 \leq ||Ax_* - b||^2$$

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$$\begin{aligned} \epsilon_g^2 &\leq \|Ax_* - b\|^2 &= \|A(x_* - x^*)\|^2 \leq \|A\|^2 \|x_* - x^*\|^2 \\ &\leq \frac{2}{\sigma(f)} \|A\|^2 (f(x^*) - f(x_*)) \end{aligned}$$

Conditions (3) with any $\epsilon_f \ge 0$ and $\epsilon_g \ge ||Ax_* - b||$ are satisfied by $\bar{y} = 0$.

Therefore, we always assume that

$$\begin{aligned} \epsilon_g^2 &\leq \|Ax_* - b\|^2 &= \|A(x_* - x^*)\|^2 \leq \|A\|^2 \|x_* - x^*\|^2 \\ &\leq \frac{2}{\sigma(f)} \|A\|^2 (f(x^*) - f(x_*)) &= 2 L(\phi) \operatorname{Out}(\mathcal{P}). \end{aligned}$$

Modified Gradient Method

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Since ϕ has Lipschitz continuous gradients, we can maximize it by a version of GM.

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Thus, conditions of Item 2 can be satisfied by bisection.

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$$\begin{split} y_{k+1} &= u_k + \frac{1}{L(\phi) + \delta} B^{-1} \nabla \phi_{\delta}(u_k), \\ u_{k+1} &= y_{k+1} + \kappa (y_{k+1} - y_k), \\ \end{split}$$
 where $\kappa = \frac{[L(\phi) + \delta]^{1/2} - \delta^{1/2}}{[L(\phi) + \delta]^{1/2} + \delta^{1/2}}.$

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Thus, in order to guarantee $(3)_b$, we need $\xi \leq \frac{2\epsilon_f \delta}{L(\phi) + \delta}$.

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 $\|\nabla\phi(y_k)\|_*$

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Hence, ξ must satisfy inequality

$$\xi \leq \min\{\frac{2\epsilon_f \delta}{L(\phi) + \delta}, \frac{(\epsilon_g - [\delta \operatorname{Out}(\mathcal{P})]^{1/2})^2}{2(L(\phi) + \delta)}\}.$$

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Choice of ξ :

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Hence, the total number of iterations for getting $(\epsilon_f, \epsilon_g)\text{-solution}$

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Complexity of objective function enters by $L(\phi) = \frac{1}{\sigma(f)} ||A||^2$, and $Out(\mathcal{P})$.

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$$f^* = \min_{Ax=b} \left[F(x) \stackrel{\text{def}}{=} -\sum_{i=1}^n \ln\left(1 - (x^{(i)})^2\right) \right].$$

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Problem: Find $x : ||x||_{\infty} \le 1$ and Ax = b. **Assumption:** For some $\hat{\epsilon} > 0$ there exist $\hat{x} : ||\hat{x}||_{\infty} \le 1 - \hat{\epsilon}$ and $A\hat{x} = b$. **New problem:** $f^* = \min_{Ax=b} \left[F(x) \stackrel{\text{def}}{=} -\sum_{i=1}^n \ln \left(1 - (x^{(i)})^2\right) \right]$. **Dual problem:** $\phi(y) = \min_x [\langle y, Ax - b \rangle + F(x)]$

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Problem: Find $x : ||x||_{\infty} \le 1$ and Ax = b.

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Complexity:

IPM(Newton): $O(Out(\mathcal{P}))$ Newton iterations.

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Problem: Find $x : ||x||_{\infty} \leq 1$ and Ax = b.

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Dual problem: $\phi(y) = \min_{x} [\langle y, Ax - b \rangle + F(x)]$ = $-\langle b, y \rangle - \sum_{i=1}^{n} \left[\sqrt{1 + \langle a_i, y \rangle^2} - 1 - \ln \frac{1 + \sqrt{1 + \langle a_i, y \rangle^2}}{2} \right] \rightarrow \max_{y}.$

Complexity:

- **IPM**(Newton): $O(Out(\mathcal{P}))$ Newton iterations.
- **FGM:** $\frac{1}{\epsilon_g} \|A\| \operatorname{Out}^{1/2}(\mathcal{P})$ gradient iterations.

Problem: Find $x : ||x||_{\infty} \leq 1$ and Ax = b.

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Dual problem: $\phi(y) = \min_{x} [\langle y, Ax - b \rangle + F(x)]$ = $-\langle b, y \rangle - \sum_{i=1}^{n} \left[\sqrt{1 + \langle a_i, y \rangle^2} - 1 - \ln \frac{1 + \sqrt{1 + \langle a_i, y \rangle^2}}{2} \right] \rightarrow \max_{y}.$

Complexity:

- **IPM**(Newton): $O(Out(\mathcal{P}))$ Newton iterations.
- **FGM**: $\frac{1}{\epsilon_q} \|A\| \operatorname{Out}^{1/2}(\mathcal{P})$ gradient iterations.

NB: $\operatorname{Out}(\mathcal{P}) \leq n \ln \frac{1}{\hat{\epsilon}}.$

Example 2. Entropy projection

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Problem:
$$\min_{x \in \Delta_n} \bigg\{ \eta(x) \stackrel{\text{def}}{=} \sum_{i=1}^n x^{(i)} \ln x^{(i)} : Ax = 0 \bigg\}.$$

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NB: $\operatorname{Out}(\mathcal{P}) = \ln n.$

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$$\phi(y) = \min_{x \in \Delta_n} \left[-\langle y, Ax \rangle + \eta(x) \right]$$

Problem:
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$$\phi(y) = \min_{x \in \Delta_n} \left[-\langle y, Ax \rangle + \eta(x) \right] = -\ln \sum_{i=1}^n e^{\langle a_i, y \rangle}$$

Problem:
$$\min_{x \in \Delta_n} \left\{ \eta(x) \stackrel{\text{def}}{=} \sum_{i=1}^n x^{(i)} \ln x^{(i)} : Ax = 0 \right\}.$$

NB: $\operatorname{Out}(\mathcal{P}) = \ln n.$

$$\phi(y) = \min_{x \in \Delta_n} \left[-\langle y, Ax \rangle + \eta(x) \right] = -\ln \sum_{i=1}^n e^{\langle a_i, y \rangle} \to \max_{y \in R^m}$$

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Problem:
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NB: $\operatorname{Out}(\mathcal{P}) = \ln n.$

$$\phi(y) = \min_{x \in \Delta_n} \left[-\langle y, Ax \rangle + \eta(x) \right] = -\ln \sum_{i=1}^n e^{\langle a_i, y \rangle} \to \max_{y \in R^m}.$$

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Complexity of dual FGM:

$$O\left(\frac{\ln^{1/2} n}{\epsilon_g} \max_{1 \le i \le n} ||a_i||_2\right)$$
 gradient iterations.

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Conclusion

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• Our complexity bounds depend on ϵ_g in an optimal way.

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Our complexity bounds depend on *ε_g* in an optimal way.
They almost do not depend on *ε_f*.

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THANK YOU FOR YOUR ATTENTION!

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