

Stochastic Equilibrium in Congested Transportation Networks

Yurii Nesterov, CORE/INMA(UCL) - Premolab/MIPT

October 17, 2013 (ORM 2013, Moscow)

Outline

- 1 Discrete choice models
- 2 Transportation networks
- 3 Characteristic functions of directed graphs
- 4 Special sets of routes
- 5 Stochastic route choice model
- 6 Stochastic equilibrium

Discrete choice models (Logit)

Discrete choice models (Logit)

1. We have k products with the costs $c^{(1)}, \dots, c^{(k)}$.

Discrete choice models (Logit)

1. We have k products with the costs $c^{(1)}, \dots, c^{(k)}$.
2. A consumer estimates the actual value of the cost with an additive error:

$$\tilde{c}^{(i)} = c^{(i)} + \epsilon_i, \quad i = 1, \dots, k.$$

Discrete choice models (Logit)

1. We have k products with the costs $c^{(1)}, \dots, c^{(k)}$.
2. A consumer estimates the actual value of the cost with an additive error:

$$\tilde{c}^{(i)} = c^{(i)} + \epsilon_i, \quad i = 1, \dots, k.$$

His choice is then $i^* : \tilde{c}^{(i^*)} = \min_{1 \leq i \leq k} \tilde{c}^{(i)}$.

Discrete choice models (Logit)

1. We have k products with the costs $c^{(1)}, \dots, c^{(k)}$.
2. A consumer estimates the actual value of the cost with an additive error:

$$\tilde{c}^{(i)} = c^{(i)} + \epsilon_i, \quad i = 1, \dots, k.$$

His choice is then $i^* : \tilde{c}^{(i^*)} = \min_{1 \leq i \leq k} \tilde{c}^{(i)}$.

3. If all ϵ_i are independent and have the same double-exponential distribution with deviation μ ,

Discrete choice models (Logit)

1. We have k products with the costs $c^{(1)}, \dots, c^{(k)}$.
2. A consumer estimates the actual value of the cost with an additive error:

$$\tilde{c}^{(i)} = c^{(i)} + \epsilon_i, \quad i = 1, \dots, k.$$

His choice is then $i^* : \tilde{c}^{(i^*)} = \min_{1 \leq i \leq k} \tilde{c}^{(i)}$.

3. If all ϵ_i are independent and have the same double-exponential distribution with deviation μ , then

$$p^{(i)} = \frac{e^{-c^{(i)}/\mu}}{\sum_{j=1}^k e^{-c^{(j)}/\mu}}, \quad i = 1, \dots, k.$$

(Logit model.)

Observation

Observation

Denote $c = (c^{(1)}, \dots, c^{(k)})^T \in R^k$, $p = (p^{(1)}, \dots, p^{(k)})^T \in R^k$,

$$\psi(c) = \ln \left(\sum_{i=1}^k e^{-c^{(i)}} \right).$$

Observation

Denote $c = (c^{(1)}, \dots, c^{(k)})^T \in \mathbb{R}^k$, $p = (p^{(1)}, \dots, p^{(k)})^T \in \mathbb{R}^k$,

$$\psi(c) = \ln \left(\sum_{i=1}^k e^{-c^{(i)}} \right).$$

Then $\psi(c)$ is *convex* in c and $p = -\nabla\psi(c)$.

Observation

Denote $c = (c^{(1)}, \dots, c^{(k)})^T \in \mathbb{R}^k$, $p = (p^{(1)}, \dots, p^{(k)})^T \in \mathbb{R}^k$,

$$\psi(c) = \ln \left(\sum_{i=1}^k e^{-c^{(i)}} \right).$$

Then $\psi(c)$ is *convex* in c and $p = -\nabla\psi(c)$.

We can go both ways:

Observation

Denote $c = (c^{(1)}, \dots, c^{(k)})^T \in R^k$, $p = (p^{(1)}, \dots, p^{(k)})^T \in R^k$,

$$\psi(c) = \ln \left(\sum_{i=1}^k e^{-c^{(i)}} \right).$$

Then $\psi(c)$ is *convex* in c and $p = -\nabla\psi(c)$.

We can go both ways:

- From a given c we can compute p : $p = -\nabla\psi(c)$.

Observation

Denote $c = (c^{(1)}, \dots, c^{(k)})^T \in \mathbb{R}^k$, $p = (p^{(1)}, \dots, p^{(k)})^T \in \mathbb{R}^k$,

$$\psi(c) = \ln \left(\sum_{i=1}^k e^{-c^{(i)}} \right).$$

Then $\psi(c)$ is *convex* in c and $p = -\nabla\psi(c)$.

We can go both ways:

- From a given c we can compute p : $p = -\nabla\psi(c)$.
- From a given p we can compute $c = c(p)$:

$$c(p) = \arg \min_c [\psi(c) + \langle p, c \rangle],$$

where $\langle x, u \rangle = \sum_{i=1}^k p^{(i)} c^{(i)}$.

Observation

Denote $c = (c^{(1)}, \dots, c^{(k)})^T \in \mathbb{R}^k$, $p = (p^{(1)}, \dots, p^{(k)})^T \in \mathbb{R}^k$,

$$\psi(c) = \ln \left(\sum_{i=1}^k e^{-c^{(i)}} \right).$$

Then $\psi(c)$ is *convex* in c and $p = -\nabla\psi(c)$.

We can go both ways:

- From a given c we can compute p : $p = -\nabla\psi(c)$.
- From a given p we can compute $c = c(p)$:

$$c(p) = \arg \min_c [\psi(c) + \langle p, c \rangle],$$

$$\text{where } \langle x, u \rangle = \sum_{i=1}^k p^{(i)} c^{(i)}.$$

NB: **1.** This minimization problem is *convex*.

Observation

Denote $c = (c^{(1)}, \dots, c^{(k)})^T \in R^k$, $p = (p^{(1)}, \dots, p^{(k)})^T \in R^k$,

$$\psi(c) = \ln \left(\sum_{i=1}^k e^{-c^{(i)}} \right).$$

Then $\psi(c)$ is *convex* in c and $p = -\nabla\psi(c)$.

We can go both ways:

- From a given c we can compute p : $p = -\nabla\psi(c)$.
- From a given p we can compute $c = c(p)$:

$$c(p) = \arg \min_c [\psi(c) + \langle p, c \rangle],$$

$$\text{where } \langle x, u \rangle = \sum_{i=1}^k p^{(i)} c^{(i)}.$$

NB: **1.** This minimization problem is *convex*.

2. $\lim_{\mu \rightarrow 0} (-\mu\psi(c/\mu)) = \min_{1 \leq i \leq k} c^{(i)}.$

Composite products

Composite products

We have m ingredients with the costs $t = (t^{(1)}, \dots, t^{(m)})^T \in R^m$.

Composite products

We have m ingredients with the costs $t = (t^{(1)}, \dots, t^{(m)})^T \in R^m$.

The cost of the product i is the sum of the costs of the ingredients:

$$c^{(i)} = \sum_{j=1}^m a_i^{(j)} t^{(j)} = \langle a_i, t \rangle, \quad i = 1, \dots, k.$$

$(a_i^{(j)})$ is the quantity of the ingredient j in the product i .)

Composite products

We have m ingredients with the costs $t = (t^{(1)}, \dots, t^{(m)})^T \in R^m$.

The cost of the product i is the sum of the costs of the ingredients:

$$c^{(i)} = \sum_{j=1}^m a_i^{(j)} t^{(j)} = \langle a_i, t \rangle, \quad i = 1, \dots, k.$$

$(a_i^{(j)})$ is the quantity of the ingredient j in the product i .)

Denote $\psi(t) = \ln \left(\sum_{i=1}^k e^{-\langle a_i, t \rangle} \right)$.

Composite products

We have m ingredients with the costs $t = (t^{(1)}, \dots, t^{(m)})^T \in R^m$.

The cost of the product i is the sum of the costs of the ingredients:

$$c^{(i)} = \sum_{j=1}^m a_i^{(j)} t^{(j)} = \langle a_i, t \rangle, \quad i = 1, \dots, k.$$

$(a_i^{(j)})$ is the quantity of the ingredient j in the product i .)

Denote $\psi(t) = \ln \left(\sum_{i=1}^k e^{-\langle a_i, t \rangle} \right)$.

Then the vector $f = -\nabla \psi(t) = \frac{\sum_{i=1}^k e^{-\langle a_i, t \rangle} a_i}{\sum_{i=1}^k e^{-\langle a_i, t \rangle}} = \sum_{i=1}^k p_i a_i$

Composite products

We have m ingredients with the costs $t = (t^{(1)}, \dots, t^{(m)})^T \in R^m$.

The cost of the product i is the sum of the costs of the ingredients:

$$c^{(i)} = \sum_{j=1}^m a_i^{(j)} t^{(j)} = \langle a_i, t \rangle, \quad i = 1, \dots, k.$$

$(a_i^{(j)})$ is the quantity of the ingredient j in the product i .)

Denote $\psi(t) = \ln \left(\sum_{i=1}^k e^{-\langle a_i, t \rangle} \right)$.

Then the vector $f = -\nabla \psi(t) = \frac{\sum_{i=1}^k e^{-\langle a_i, t \rangle} a_i}{\sum_{i=1}^k e^{-\langle a_i, t \rangle}} = \sum_{i=1}^k p_i a_i$

gives the expected consumption of the ingredients, which corresponds to the prices t .

Composite products

We have m ingredients with the costs $t = (t^{(1)}, \dots, t^{(m)})^T \in R^m$.

The cost of the product i is the sum of the costs of the ingredients:

$$c^{(i)} = \sum_{j=1}^m a_i^{(j)} t^{(j)} = \langle a_i, t \rangle, \quad i = 1, \dots, k.$$

$(a_i^{(j)})$ is the quantity of the ingredient j in the product i .)

Denote $\psi(t) = \ln \left(\sum_{i=1}^k e^{-\langle a_i, t \rangle} \right)$.

Then the vector $f = -\nabla \psi(t) = \frac{\sum_{i=1}^k e^{-\langle a_i, t \rangle} a_i}{\sum_{i=1}^k e^{-\langle a_i, t \rangle}} = \sum_{i=1}^k p_i a_i$

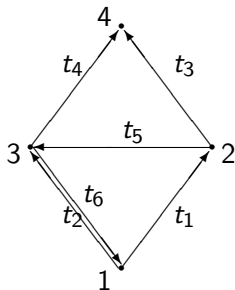
gives the expected consumption of the ingredients, which corresponds to the prices t .

Since $\psi(t)$ is convex, we can go in both directions:

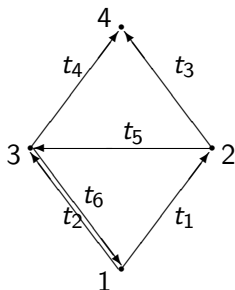
$$t \Rightarrow f(t), \quad f \Rightarrow t(f).$$

Transportation networks: Example

Transportation networks: Example

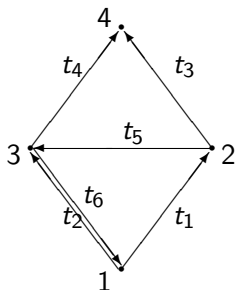


Transportation networks: Example



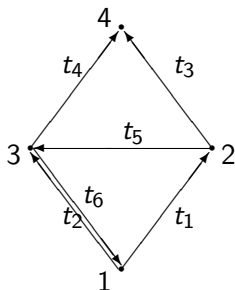
Strategies (routes from 1 to 4):

Transportation networks: Example



Strategies (routes from 1 to 4):
 $a_1 = (0, 1, 0, 1, 0, 0)^T$, $c_1(t) = t_2 + t_4$,

Transportation networks: Example

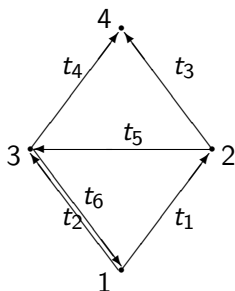


Strategies (routes from 1 to 4):

$$a_1 = (0, 1, 0, 1, 0, 0)^T, c_1(t) = t_2 + t_4,$$

$$a_2 = (1, 0, 1, 0, 0, 0)^T, c_2(t) = t_1 + t_3,$$

Transportation networks: Example



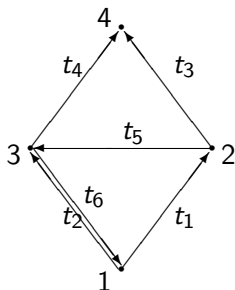
Strategies (routes from 1 to 4):

$$a_1 = (0, 1, 0, 1, 0, 0)^T, c_1(t) = t_2 + t_4,$$

$$a_2 = (1, 0, 1, 0, 0, 0)^T, c_2(t) = t_1 + t_3,$$

$$a_3 = (1, 0, 0, 1, 1, 0)^T, c_3(t) = t_1 + t_4 + t_5.$$

Transportation networks: Example



Strategies (routes from 1 to 4):

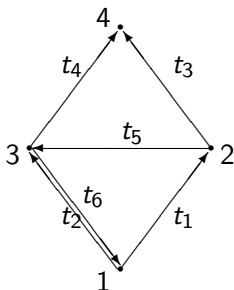
$$a_1 = (0, 1, 0, 1, 0, 0)^T, c_1(t) = t_2 + t_4,$$

$$a_2 = (1, 0, 1, 0, 0, 0)^T, c_2(t) = t_1 + t_3,$$

$$a_3 = (1, 0, 0, 1, 1, 0)^T, c_3(t) = t_1 + t_4 + t_5.$$

Potential function: $\psi(t) = \ln (e^{-c_1(t)} + e^{-c_2(t)} + e^{-c_3(t)})$.

Transportation networks: Example



Strategies (routes from 1 to 4):

$$a_1 = (0, 1, 0, 1, 0, 0)^T, c_1(t) = t_2 + t_4,$$

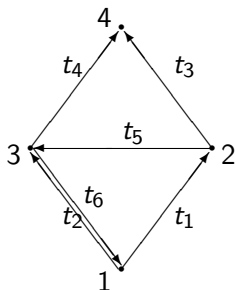
$$a_2 = (1, 0, 1, 0, 0, 0)^T, c_2(t) = t_1 + t_3,$$

$$a_3 = (1, 0, 0, 1, 1, 0)^T, c_3(t) = t_1 + t_4 + t_5.$$

Potential function: $\psi(t) = \ln (e^{-c_1(t)} + e^{-c_2(t)} + e^{-c_3(t)})$.

Then the gradient $f = -\nabla\psi(t) = p_1 a_1 + p_2 a_2 + p_3 a_3$

Transportation networks: Example



Strategies (routes from 1 to 4):

$$a_1 = (0, 1, 0, 1, 0, 0)^T, c_1(t) = t_2 + t_4,$$

$$a_2 = (1, 0, 1, 0, 0, 0)^T, c_2(t) = t_1 + t_3,$$

$$a_3 = (1, 0, 0, 1, 1, 0)^T, c_3(t) = t_1 + t_4 + t_5.$$

Potential function: $\psi(t) = \ln (e^{-c_1(t)} + e^{-c_2(t)} + e^{-c_3(t)})$.

Then the gradient $f = -\nabla\psi(t) = p_1 a_1 + p_2 a_2 + p_3 a_3$

is the *expected flow* on the arcs (with respect to given time t).

Sets of routes in general networks

Sets of routes in general networks

Consider the network \mathcal{N} with n nodes and m arcs:

$$\mathcal{A} = \{(i_1, j_1), \dots, (i_m, j_m) : 1 \leq i_k, j_k \leq n, k = 1, \dots, m\}.$$

Sets of routes in general networks

Consider the network \mathcal{N} with n nodes and m arcs:

$$\mathcal{A} = \{(i_1, j_1), \dots, (i_m, j_m) : 1 \leq i_k, j_k \leq n, k = 1, \dots, m\}.$$

An ordered set of pairs from \mathcal{A} : $r = \{(i_0, i_1), (i_1, i_2), \dots, (i_{p-1}, i_p)\}$ is called the *route* in \mathcal{N} , connecting i_0 and i_p .

Sets of routes in general networks

Consider the network \mathcal{N} with n nodes and m arcs:

$$\mathcal{A} = \{(i_1, j_1), \dots, (i_m, j_m) : 1 \leq i_k, j_k \leq n, k = 1, \dots, m\}.$$

An ordered set of pairs from \mathcal{A} : $r = \{(i_0, i_1), (i_1, i_2), \dots, (i_{p-1}, i_p)\}$ is called the *route* in \mathcal{N} , connecting i_0 and i_p .

The value $l(r) = p$ is called the length of the route.

Sets of routes in general networks

Consider the network \mathcal{N} with n nodes and m arcs:

$$\mathcal{A} = \{(i_1, j_1), \dots, (i_m, j_m) : 1 \leq i_k, j_k \leq n, k = 1, \dots, m\}.$$

An ordered set of pairs from \mathcal{A} : $r = \{(i_0, i_1), (i_1, i_2), \dots, (i_{p-1}, i_p)\}$ is called the *route* in \mathcal{N} , connecting i_0 and i_p .

The value $l(r) = p$ is called the length of the route.

Denote by $a(r) \in R^m$ the vector:

$$a(r)^{(k)} = \begin{cases} 1, & \text{if } (i_k, j_k) \in r, \\ 0, & \text{otherwise.} \end{cases} \quad k = 1, \dots, m.$$

Sets of routes in general networks

Consider the network \mathcal{N} with n nodes and m arcs:

$$\mathcal{A} = \{(i_1, j_1), \dots, (i_m, j_m) : 1 \leq i_k, j_k \leq n, k = 1, \dots, m\}.$$

An ordered set of pairs from \mathcal{A} : $r = \{(i_0, i_1), (i_1, i_2), \dots, (i_{p-1}, i_p)\}$ is called the *route* in \mathcal{N} , connecting i_0 and i_p .

The value $l(r) = p$ is called the length of the route.

Denote by $a(r) \in R^m$ the vector:

$$a(r)^{(k)} = \begin{cases} 1, & \text{if } (i_k, j_k) \in r, \\ 0, & \text{otherwise.} \end{cases} \quad k = 1, \dots, m.$$

Then for any $t \in R^m$ we can define the cost $c_r(t) = \langle a(r), t \rangle$.

Sets of routes in general networks

Consider the network \mathcal{N} with n nodes and m arcs:

$$\mathcal{A} = \{(i_1, j_1), \dots, (i_m, j_m) : 1 \leq i_k, j_k \leq n, k = 1, \dots, m\}.$$

An ordered set of pairs from \mathcal{A} : $r = \{(i_0, i_1), (i_1, i_2), \dots, (i_{p-1}, i_p)\}$ is called the *route* in \mathcal{N} , connecting i_0 and i_p .

The value $l(r) = p$ is called the length of the route.

Denote by $a(r) \in R^m$ the vector:

$$a(r)^{(k)} = \begin{cases} 1, & \text{if } (i_k, j_k) \in r, \\ 0, & \text{otherwise.} \end{cases} \quad k = 1, \dots, m.$$

Then for any $t \in R^m$ we can define the cost $c_r(t) = \langle a(r), t \rangle$.

Def. Let \mathcal{R} be some set of routes in \mathcal{N} .

Sets of routes in general networks

Consider the network \mathcal{N} with n nodes and m arcs:

$$\mathcal{A} = \{(i_1, j_1), \dots, (i_m, j_m) : 1 \leq i_k, j_k \leq n, k = 1, \dots, m\}.$$

An ordered set of pairs from \mathcal{A} : $r = \{(i_0, i_1), (i_1, i_2), \dots, (i_{p-1}, i_p)\}$ is called the *route* in \mathcal{N} , connecting i_0 and i_p .

The value $l(r) = p$ is called the length of the route.

Denote by $a(r) \in R^m$ the vector:

$$a(r)^{(k)} = \begin{cases} 1, & \text{if } (i_k, j_k) \in r, \\ 0, & \text{otherwise.} \end{cases} \quad k = 1, \dots, m.$$

Then for any $t \in R^m$ we can define the cost $c_r(t) = \langle a(r), t \rangle$.

Def. Let \mathcal{R} be some set of routes in \mathcal{N} . We call

$$g_{\mathcal{R}}(t) = \sum_{r \in \mathcal{R}} e^{-c_r(t)}$$

the characteristic function of \mathcal{R} .

Sets of routes in general networks

Consider the network \mathcal{N} with n nodes and m arcs:

$$\mathcal{A} = \{(i_1, j_1), \dots, (i_m, j_m) : 1 \leq i_k, j_k \leq n, k = 1, \dots, m\}.$$

An ordered set of pairs from \mathcal{A} : $r = \{(i_0, i_1), (i_1, i_2), \dots, (i_{p-1}, i_p)\}$ is called the *route* in \mathcal{N} , connecting i_0 and i_p .

The value $l(r) = p$ is called the length of the route.

Denote by $a(r) \in R^m$ the vector:

$$a(r)^{(k)} = \begin{cases} 1, & \text{if } (i_k, j_k) \in r, \\ 0, & \text{otherwise.} \end{cases} \quad k = 1, \dots, m.$$

Then for any $t \in R^m$ we can define the cost $c_r(t) = \langle a(r), t \rangle$.

Def. Let \mathcal{R} be some set of routes in \mathcal{N} . We call

$$g_{\mathcal{R}}(t) = \sum_{r \in \mathcal{R}} e^{-c_r(t)}$$

the characteristic function of \mathcal{R} . For $\mathcal{R} = \emptyset$ define $g_{\emptyset}(t) \equiv 0$.

Properties of potential functions

Properties of potential functions

Def. The function $\psi_{\mathcal{R}}(t) = \ln g_{\mathcal{R}}(t)$ is called potential function of the set of routes \mathcal{R} .

Properties of potential functions

Def. The function $\psi_{\mathcal{R}}(t) = \ln g_{\mathcal{R}}(t)$ is called potential function of the set of routes \mathcal{R} .

Let \mathcal{R} be non-empty and finite. Denote

$$SP_{\mathcal{R}}(t) = \min_r \{c_r(t) : r \in \mathcal{R}\}.$$

Properties of potential functions

Def. The function $\psi_{\mathcal{R}}(t) = \ln g_{\mathcal{R}}(t)$ is called potential function of the set of routes \mathcal{R} .

Let \mathcal{R} be non-empty and finite. Denote

$$SP_{\mathcal{R}}(t) = \min_r \{c_r(t) : r \in \mathcal{R}\}. \text{ (It is concave.)}$$

Properties of potential functions

Def. The function $\psi_{\mathcal{R}}(t) = \ln g_{\mathcal{R}}(t)$ is called potential function of the set of routes \mathcal{R} .

Let \mathcal{R} be non-empty and finite. Denote

$$SP_{\mathcal{R}}(t) = \min_r \{c_r(t) : r \in \mathcal{R}\}. \text{ (It is concave.)}$$

Theorem.

Properties of potential functions

Def. The function $\psi_{\mathcal{R}}(t) = \ln g_{\mathcal{R}}(t)$ is called potential function of the set of routes \mathcal{R} .

Let \mathcal{R} be non-empty and finite. Denote

$$SP_{\mathcal{R}}(t) = \min_r \{c_r(t) : r \in \mathcal{R}\}. \text{ (It is concave.)}$$

Theorem. 1. $\psi_{\mathcal{R}}(t)$ is a convex function.

Properties of potential functions

Def. The function $\psi_{\mathcal{R}}(t) = \ln g_{\mathcal{R}}(t)$ is called potential function of the set of routes \mathcal{R} .

Let \mathcal{R} be non-empty and finite. Denote

$$SP_{\mathcal{R}}(t) = \min_r \{c_r(t) : r \in \mathcal{R}\}. \text{ (It is concave.)}$$

Theorem. 1. $\psi_{\mathcal{R}}(t)$ is a convex function.

2. The vector $-\nabla\psi_{\mathcal{R}}(t)$ is the expected flow in the network.

Properties of potential functions

Def. The function $\psi_{\mathcal{R}}(t) = \ln g_{\mathcal{R}}(t)$ is called potential function of the set of routes \mathcal{R} .

Let \mathcal{R} be non-empty and finite. Denote

$$SP_{\mathcal{R}}(t) = \min_r \{c_r(t) : r \in \mathcal{R}\}. \text{ (It is concave.)}$$

Theorem. 1. $\psi_{\mathcal{R}}(t)$ is a convex function.

2. The vector $-\nabla\psi_{\mathcal{R}}(t)$ is the expected flow in the network.

3. For any $t, \bar{t} \in R^m$ we have $\lim_{\mu \rightarrow \infty} \left(-\frac{1}{\mu} \psi_{\mathcal{R}}(\bar{t} + \mu t) \right) = SP_{\mathcal{R}}(t)$.

Properties of potential functions

Def. The function $\psi_{\mathcal{R}}(t) = \ln g_{\mathcal{R}}(t)$ is called potential function of the set of routes \mathcal{R} .

Let \mathcal{R} be non-empty and finite. Denote

$$SP_{\mathcal{R}}(t) = \min_r \{c_r(t) : r \in \mathcal{R}\}. \text{ (It is concave.)}$$

Theorem. 1. $\psi_{\mathcal{R}}(t)$ is a convex function.

2. The vector $-\nabla\psi_{\mathcal{R}}(t)$ is the expected flow in the network.

3. For any $t, \bar{t} \in R^m$ we have $\lim_{\mu \rightarrow \infty} \left(-\frac{1}{\mu} \psi_{\mathcal{R}}(\bar{t} + \mu t) \right) = SP_{\mathcal{R}}(t)$.

Main property: for $\mathcal{R} = \mathcal{R}_1 \cup \mathcal{R}_2$ with $\mathcal{R}_1 \cap \mathcal{R}_2 = \emptyset$,

Properties of potential functions

Def. The function $\psi_{\mathcal{R}}(t) = \ln g_{\mathcal{R}}(t)$ is called potential function of the set of routes \mathcal{R} .

Let \mathcal{R} be non-empty and finite. Denote

$$SP_{\mathcal{R}}(t) = \min_r \{c_r(t) : r \in \mathcal{R}\}. \text{ (It is concave.)}$$

Theorem. 1. $\psi_{\mathcal{R}}(t)$ is a convex function.

2. The vector $-\nabla\psi_{\mathcal{R}}(t)$ is the expected flow in the network.

3. For any $t, \bar{t} \in R^m$ we have $\lim_{\mu \rightarrow \infty} \left(-\frac{1}{\mu}\psi_{\mathcal{R}}(\bar{t} + \mu t)\right) = SP_{\mathcal{R}}(t)$.

Main property: for $\mathcal{R} = \mathcal{R}_1 \cup \mathcal{R}_2$ with $\mathcal{R}_1 \cap \mathcal{R}_2 = \emptyset$, we have

$$\psi_{\mathcal{R}}(t) = \ln \left(e^{\psi_{\mathcal{R}_1}(t)} + e^{\psi_{\mathcal{R}_2}(t)} \right).$$

Main difficulties

Main difficulties

1. In general networks, the number of acyclic routes is exponentially big.

Main difficulties

1. In general networks, the number of acyclic routes is exponentially big.
2. The number of routes with cycles is infinite.

Main difficulties

1. In general networks, the number of acyclic routes is exponentially big.
2. The number of routes with cycles is infinite.

*Can we compute characteristic functions
of some reasonably big sets of routes?*

Special sets of routes

Special sets of routes

Let us fix two nodes i and j .

Special sets of routes

Let us fix two nodes i and j . Denote:

$\mathcal{R}_{i,j}^p$ the set of all routes of length p
connecting j and i .

Special sets of routes

Let us fix two nodes i and j . Denote:

$\mathcal{R}_{i,j}^p$ the set of all routes of length p connecting j and i .

$$\widehat{\mathcal{R}}_{i,j}^L = \bigcup_{p=1}^L \mathcal{R}_{i,j}^p,$$

Special sets of routes

Let us fix two nodes i and j . Denote:

$\mathcal{R}_{i,j}^p$ the set of all routes of length p connecting j and i .

$$\widehat{\mathcal{R}}_{i,j}^L = \bigcup_{p=1}^L \mathcal{R}_{i,j}^p,$$

$$\widetilde{\mathcal{R}}_{i,j} = \bigcup_{p=1}^{\infty} \mathcal{R}_{i,j}^p.$$

Special sets of routes

Let us fix two nodes i and j . Denote:

$\mathcal{R}_{i,j}^p$ the set of all routes of length p connecting j and i .

$$\widehat{\mathcal{R}}_{i,j}^L = \bigcup_{p=1}^L \mathcal{R}_{i,j}^p,$$

$$\widetilde{\mathcal{R}}_{i,j} = \bigcup_{p=1}^{\infty} \mathcal{R}_{i,j}^p.$$

Denote by $E(t)$ the following $n \times n$ -matrix:

Special sets of routes

Let us fix two nodes i and j . Denote:

$\mathcal{R}_{i,j}^p$ the set of all routes of length p connecting j and i .

$$\widehat{\mathcal{R}}_{i,j}^L = \bigcup_{p=1}^L \mathcal{R}_{i,j}^p,$$

$$\widetilde{\mathcal{R}}_{i,j} = \bigcup_{p=1}^{\infty} \mathcal{R}_{i,j}^p.$$

Denote by $E(t)$ the following $n \times n$ -matrix:

$$E(t)^{(i,j)} = \begin{cases} e^{-t(\alpha)}, & \text{if } \alpha \equiv (j, i) \in \mathcal{A}, \\ 0, & \text{otherwise.} \end{cases}$$

Special sets of routes

Let us fix two nodes i and j . Denote:

$\mathcal{R}_{i,j}^p$ the set of all routes of length p connecting j and i .

$$\widehat{\mathcal{R}}_{i,j}^L = \bigcup_{p=1}^L \mathcal{R}_{i,j}^p,$$

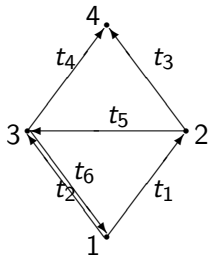
$$\widetilde{\mathcal{R}}_{i,j} = \bigcup_{p=1}^{\infty} \mathcal{R}_{i,j}^p.$$

Denote by $E(t)$ the following $n \times n$ -matrix:

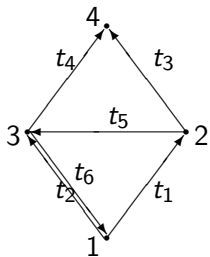
$$E(t)^{(i,j)} = \begin{cases} e^{-t(\alpha)}, & \text{if } \alpha \equiv (j, i) \in \mathcal{A}, \\ 0, & \text{otherwise.} \end{cases}$$

Example

Example

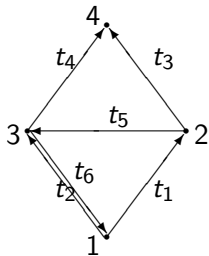


Example



Then

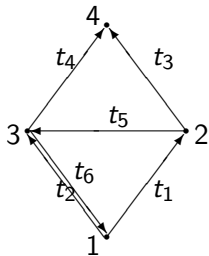
Example



Then

$$E(t) = \begin{pmatrix} 0 & 0 & e^{-t^{(6)}} & 0 \\ \end{pmatrix}$$

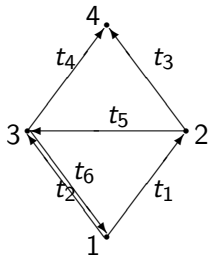
Example



Then

$$E(t) = \begin{pmatrix} 0 & 0 & e^{-t^{(6)}} & 0 \\ e^{-t^{(1)}} & 0 & 0 & 0 \end{pmatrix}$$

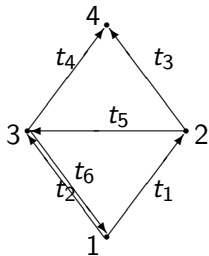
Example



Then

$$E(t) = \begin{pmatrix} 0 & 0 & e^{-t^{(6)}} & 0 \\ e^{-t^{(1)}} & 0 & 0 & 0 \\ e^{-t^{(2)}} & e^{-t^{(5)}} & 0 & 0 \end{pmatrix}$$

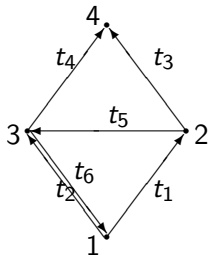
Example



Then

$$E(t) = \begin{pmatrix} 0 & 0 & e^{-t^{(6)}} & 0 \\ e^{-t^{(1)}} & 0 & 0 & 0 \\ e^{-t^{(2)}} & e^{-t^{(5)}} & 0 & 0 \\ 0 & e^{-t^{(3)}} & e^{-t^{(4)}} & 0 \end{pmatrix}.$$

Example

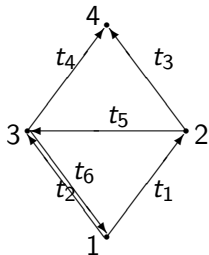


Then

$$E(t) = \begin{pmatrix} 0 & 0 & e^{-t^{(6)}} & 0 \\ e^{-t^{(1)}} & 0 & 0 & 0 \\ e^{-t^{(2)}} & e^{-t^{(5)}} & 0 & 0 \\ 0 & e^{-t^{(3)}} & e^{-t^{(4)}} & 0 \end{pmatrix}.$$

$$E^2(t)$$

Example

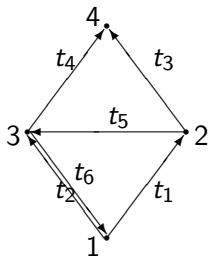


Then

$$E(t) = \begin{pmatrix} 0 & 0 & e^{-t^{(6)}} & 0 \\ e^{-t^{(1)}} & 0 & 0 & 0 \\ e^{-t^{(2)}} & e^{-t^{(5)}} & 0 & 0 \\ 0 & e^{-t^{(3)}} & e^{-t^{(4)}} & 0 \end{pmatrix}.$$

$$E^2(t) = \begin{pmatrix} e^{-t^{(2)}-t^{(6)}} & e^{-t^{(5)}-t^{(6)}} & 0 & 0 \end{pmatrix}$$

Example

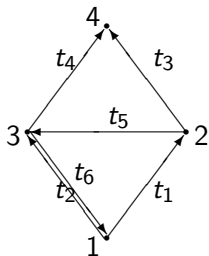


Then

$$E(t) = \begin{pmatrix} 0 & 0 & e^{-t^{(6)}} & 0 \\ e^{-t^{(1)}} & 0 & 0 & 0 \\ e^{-t^{(2)}} & e^{-t^{(5)}} & 0 & 0 \\ 0 & e^{-t^{(3)}} & e^{-t^{(4)}} & 0 \end{pmatrix}.$$

$$E^2(t) = \begin{pmatrix} e^{-t^{(2)}-t^{(6)}} & e^{-t^{(5)}-t^{(6)}} & 0 & 0 \\ 0 & 0 & e^{-t^{(1)}-t^{(6)}} & 0 \end{pmatrix}$$

Example

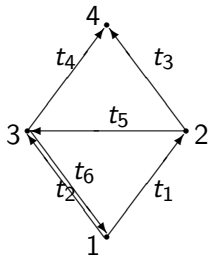


Then

$$E(t) = \begin{pmatrix} 0 & 0 & e^{-t^{(6)}} & 0 \\ e^{-t^{(1)}} & 0 & 0 & 0 \\ e^{-t^{(2)}} & e^{-t^{(5)}} & 0 & 0 \\ 0 & e^{-t^{(3)}} & e^{-t^{(4)}} & 0 \end{pmatrix}.$$

$$E^2(t) = \begin{pmatrix} e^{-t^{(2)}-t^{(6)}} & e^{-t^{(5)}-t^{(6)}} & 0 & 0 \\ 0 & 0 & e^{-t^{(1)}-t^{(6)}} & 0 \\ e^{-t^{(1)}-t^{(5)}} & 0 & e^{-t^{(2)}-t^{(6)}} & 0 \end{pmatrix}$$

Example



Then

$$E(t) = \begin{pmatrix} 0 & 0 & e^{-t(6)} & 0 \\ e^{-t(1)} & 0 & 0 & 0 \\ e^{-t(2)} & e^{-t(5)} & 0 & 0 \\ 0 & e^{-t(3)} & e^{-t(4)} & 0 \end{pmatrix}.$$

$$E^2(t) = \begin{pmatrix} e^{-t(2)-t(6)} & e^{-t(5)-t(6)} & 0 & 0 \\ 0 & 0 & e^{-t(1)-t(6)} & 0 \\ e^{-t(1)-t(5)} & 0 & e^{-t(2)-t(6)} & 0 \\ e^{-t(1)-t(3)} + e^{-t(2)-t(4)} & e^{-t(4)-t(5)} & 0 & 0 \end{pmatrix}.$$

Characteristic matrix functions

Characteristic matrix functions

Theorem. Each element of matrix function $E^p(t)$, $p \geq 1$, is the characteristic function for corresponding set of routs $\mathcal{R}_{i,j}^p$.

Characteristic matrix functions

Theorem. Each element of matrix function $E^p(t)$, $p \geq 1$, is the characteristic function for corresponding set of routs $\mathcal{R}_{i,j}^p$.

Therefore,

Characteristic matrix functions

Theorem. Each element of matrix function $E^p(t)$, $p \geq 1$, is the characteristic function for corresponding set of routs $\mathcal{R}_{i,j}^p$.

Therefore,

- The elements of matrix $E_L(t) = \sum_{p=1}^L E^p(t)$ are log-convex characteristic functions for $\widehat{\mathcal{R}}_{i,j}^L$.

Characteristic matrix functions

Theorem. Each element of matrix function $E^p(t)$, $p \geq 1$, is the characteristic function for corresponding set of routs $\mathcal{R}_{i,j}^p$.

Therefore,

- The elements of matrix $E_L(t) = \sum_{p=1}^L E^p(t)$ are log-convex characteristic functions for $\widehat{\mathcal{R}}_{i,j}^L$.
- The elements of matrix $\tilde{E}(t) = (I - E(t))^{-1} - I$ are the characteristic functions for $\widetilde{\mathcal{R}}_{i,j}$.

Characteristic matrix functions

Theorem. Each element of matrix function $E^p(t)$, $p \geq 1$, is the characteristic function for corresponding set of routs $\mathcal{R}_{i,j}^p$.

Therefore,

- The elements of matrix $E_L(t) = \sum_{p=1}^L E^p(t)$ are log-convex characteristic functions for $\widehat{\mathcal{R}}_{i,j}^L$.
- The elements of matrix $\tilde{E}(t) = (I - E(t))^{-1} - I$ are the characteristic functions for $\widetilde{\mathcal{R}}_{i,j}$.

Properties:

Characteristic matrix functions

Theorem. Each element of matrix function $E^p(t)$, $p \geq 1$, is the characteristic function for corresponding set of routs $\mathcal{R}_{i,j}^p$.

Therefore,

- The elements of matrix $E_L(t) = \sum_{p=1}^L E^p(t)$ are log-convex characteristic functions for $\widehat{\mathcal{R}}_{i,j}^L$.
- The elements of matrix $\tilde{E}(t) = (I - E(t))^{-1} - I$ are the characteristic functions for $\widetilde{\mathcal{R}}_{i,j}$.

Properties:

1. $E^p(0)^{(i,j)}$ is the number of routes of length p connecting j and i .

Characteristic matrix functions

Theorem. Each element of matrix function $E^p(t)$, $p \geq 1$, is the characteristic function for corresponding set of routs $\mathcal{R}_{i,j}^p$.

Therefore,

- The elements of matrix $E_L(t) = \sum_{p=1}^L E^p(t)$ are log-convex characteristic functions for $\widehat{\mathcal{R}}_{i,j}^L$.
- The elements of matrix $\tilde{E}(t) = (I - E(t))^{-1} - I$ are the characteristic functions for $\widetilde{\mathcal{R}}_{i,j}$.

Properties:

1. $E^p(0)^{(i,j)}$ is the number of routes of length p connecting j and i .
2. $\tilde{E}(t)^{(i,j)} \neq 0$ if and only if j and i are connected.

Asymptotic potential function

Asymptotic potential function

Denote by $\Psi(t)$ the matrix with the following entries

$$\Psi(t)^{(i,j)} = \ln \left((I - E(t))^{-1} - I \right)^{(i,j)}, \quad i, j = 1, \dots, n.$$

Asymptotic potential function

Denote by $\Psi(t)$ the matrix with the following entries

$$\Psi(t)^{(i,j)} = \ln \left((I - E(t))^{-1} - I \right)^{(i,j)}, \quad i, j = 1, \dots, n.$$

Denote $\rho(t) = \max_{1 \leq j \leq n} |\lambda_j(E(t))|$.

Asymptotic potential function

Denote by $\Psi(t)$ the matrix with the following entries

$$\Psi(t)^{(i,j)} = \ln \left((I - E(t))^{-1} - I \right)^{(i,j)}, \quad i, j = 1, \dots, n.$$

Denote $\rho(t) = \max_{1 \leq j \leq n} |\lambda_j(E(t))|$.

Let us assume that any pair of nodes in \mathcal{N} is connected.

Asymptotic potential function

Denote by $\Psi(t)$ the matrix with the following entries

$$\Psi(t)^{(i,j)} = \ln \left((I - E(t))^{-1} - I \right)^{(i,j)}, \quad i, j = 1, \dots, n.$$

Denote $\rho(t) = \max_{1 \leq j \leq n} |\lambda_j(E(t))|$.

Let us assume that any pair of nodes in \mathcal{N} is connected. Then:

1. $\text{dom } \Psi \equiv \{t : \rho(t) < 1\} \supseteq \{t : t^{(\alpha)} > \ln n, \forall \alpha \in \mathcal{A}\}$.

Asymptotic potential function

Denote by $\Psi(t)$ the matrix with the following entries

$$\Psi(t)^{(i,j)} = \ln \left((I - E(t))^{-1} - I \right)^{(i,j)}, \quad i, j = 1, \dots, n.$$

Denote $\rho(t) = \max_{1 \leq j \leq n} |\lambda_j(E(t))|$.

Let us assume that any pair of nodes in \mathcal{N} is connected. Then:

1. $\text{dom } \Psi \equiv \{t : \rho(t) < 1\} \supseteq \{t : t^{(\alpha)} > \ln n, \forall \alpha \in \mathcal{A}\}$.
2. Each entry $\Psi(t)^{(i,j)}$ is convex in t .

Asymptotic potential function

Denote by $\Psi(t)$ the matrix with the following entries

$$\Psi(t)^{(i,j)} = \ln \left((I - E(t))^{-1} - I \right)^{(i,j)}, \quad i, j = 1, \dots, n.$$

Denote $\rho(t) = \max_{1 \leq j \leq n} |\lambda_j(E(t))|$.

Let us assume that any pair of nodes in \mathcal{N} is connected. Then:

1. $\text{dom } \Psi \equiv \{t : \rho(t) < 1\} \supseteq \{t : t^{(\alpha)} > \ln n, \forall \alpha \in \mathcal{A}\}$.
2. Each entry $\Psi(t)^{(i,j)}$ is convex in t .
3. For any $\bar{t} \in \text{dom } \Psi$ and $t \geq 0$ we have

$$\lim_{\mu \rightarrow 0} \mu \Psi(\bar{t} + t/\mu)^{(i,j)} = -SP_{j,i}(t).$$

Asymptotic potential function

Denote by $\Psi(t)$ the matrix with the following entries

$$\Psi(t)^{(i,j)} = \ln \left((I - E(t))^{-1} - I \right)^{(i,j)}, \quad i, j = 1, \dots, n.$$

Denote $\rho(t) = \max_{1 \leq j \leq n} |\lambda_j(E(t))|$.

Let us assume that any pair of nodes in \mathcal{N} is connected. Then:

1. $\text{dom } \Psi \equiv \{t : \rho(t) < 1\} \supseteq \{t : t^{(\alpha)} > \ln n, \forall \alpha \in \mathcal{A}\}$.
2. Each entry $\Psi(t)^{(i,j)}$ is convex in t .
3. For any $\bar{t} \in \text{dom } \Psi$ and $t \geq 0$ we have

$$\lim_{\mu \rightarrow 0} \mu \Psi(\bar{t} + t/\mu)^{(i,j)} = -SP_{j,i}(t).$$

Derivatives:

Asymptotic potential function

Denote by $\Psi(t)$ the matrix with the following entries

$$\Psi(t)^{(i,j)} = \ln \left((I - E(t))^{-1} - I \right)^{(i,j)}, \quad i, j = 1, \dots, n.$$

Denote $\rho(t) = \max_{1 \leq j \leq n} |\lambda_j(E(t))|$.

Let us assume that any pair of nodes in \mathcal{N} is connected. Then:

1. $\text{dom } \Psi \equiv \{t : \rho(t) < 1\} \supseteq \{t : t^{(\alpha)} > \ln n, \forall \alpha \in \mathcal{A}\}$.
2. Each entry $\Psi(t)^{(i,j)}$ is convex in t .
3. For any $\bar{t} \in \text{dom } \Psi$ and $t \geq 0$ we have

$$\lim_{\mu \rightarrow 0} \mu \Psi(\bar{t} + t/\mu)^{(i,j)} = -SP_{j,i}(t).$$

Derivatives: for $\alpha = (k_1, k_2)$ we have

$$\frac{d\Psi^{(i,j)}(t)}{dt^{(\alpha)}} = \frac{e^{-t^{(\alpha)}}}{\bar{E}(t)^{(i,j)}} \langle (I - E(t))^{-1} e_{k_2}, e_i \rangle \cdot \langle (I - E(t))^{-1} e_j, e_{k_1} \rangle,$$

where e_k are coordinate vectors in R^m .

Asymptotic potential function

Denote by $\Psi(t)$ the matrix with the following entries

$$\Psi(t)^{(i,j)} = \ln \left((I - E(t))^{-1} - I \right)^{(i,j)}, \quad i, j = 1, \dots, n.$$

Denote $\rho(t) = \max_{1 \leq j \leq n} |\lambda_j(E(t))|$.

Let us assume that any pair of nodes in \mathcal{N} is connected. Then:

1. $\text{dom } \Psi \equiv \{t : \rho(t) < 1\} \supseteq \{t : t^{(\alpha)} > \ln n, \forall \alpha \in \mathcal{A}\}$.
2. Each entry $\Psi(t)^{(i,j)}$ is convex in t .
3. For any $\bar{t} \in \text{dom } \Psi$ and $t \geq 0$ we have

$$\lim_{\mu \rightarrow 0} \mu \Psi(\bar{t} + t/\mu)^{(i,j)} = -SP_{j,i}(t).$$

Derivatives: for $\alpha = (k_1, k_2)$ we have

$$\frac{d\Psi^{(i,j)}(t)}{dt^{(\alpha)}} = \frac{e^{-t^{(\alpha)}}}{\tilde{E}(t)^{(i,j)}} \langle (I - E(t))^{-1} e_{k_2}, e_i \rangle \cdot \langle (I - E(t))^{-1} e_j, e_{k_1} \rangle,$$

where e_k are coordinate vectors in R^m .

This is the expected flow $j \rightarrow i$ passing through α .

Routes with bounded length

Routes with bounded length

For the source j and length of the route p define the functions:

$$\left. \begin{aligned} a_p^{(i)}(t) &= \mu \ln g_{\mathcal{R}_{i,j}^p}(t/\mu) \\ b_p^{(i)}(t) &= \mu \ln g_{\widehat{\mathcal{R}}_{i,j}^p}(t/\mu) \end{aligned} \right\}, \quad i = 1, \dots, n,$$

Routes with bounded length

For the source j and length of the route p define the functions:

$$\left. \begin{aligned} a_p^{(i)}(t) &= \mu \ln g_{\mathcal{R}_{i,j}^p}(t/\mu) \\ b_p^{(i)}(t) &= \mu \ln g_{\widehat{\mathcal{R}}_{i,j}^p}(t/\mu) \end{aligned} \right\}, \quad i = 1, \dots, n,$$

Initialization: for $i = 1, \dots, n$ set

$$a_1^{(i)}(t) = b_1^{(i)}(t) = \begin{cases} -t^{(\alpha)}, & \text{if } \alpha = (j, i) \in \mathcal{A}, \\ -\infty, & \text{otherwise.} \end{cases}$$

Routes with bounded length

For the source j and length of the route p define the functions:

$$\left. \begin{aligned} a_p^{(i)}(t) &= \mu \ln g_{\mathcal{R}_{i,j}^p}(t/\mu) \\ b_p^{(i)}(t) &= \mu \ln g_{\widehat{\mathcal{R}}_{i,j}^p}(t/\mu) \end{aligned} \right\}, \quad i = 1, \dots, n,$$

Initialization: for $i = 1, \dots, n$ set

$$a_1^{(i)}(t) = b_1^{(i)}(t) = \begin{cases} -t^{(\alpha)}, & \text{if } \alpha = (j, i) \in \mathcal{A}, \\ -\infty, & \text{otherwise.} \end{cases}$$

Iteration ($p = 1, \dots, L - 1$): for $i = 1, \dots, n$ compute

Routes with bounded length

For the source j and length of the route p define the functions:

$$\left. \begin{aligned} a_p^{(i)}(t) &= \mu \ln g_{\mathcal{R}_{i,j}^p}(t/\mu) \\ b_p^{(i)}(t) &= \mu \ln g_{\widehat{\mathcal{R}}_{i,j}^p}(t/\mu) \end{aligned} \right\}, \quad i = 1, \dots, n,$$

Initialization: for $i = 1, \dots, n$ set

$$a_1^{(i)}(t) = b_1^{(i)}(t) = \begin{cases} -t^{(\alpha)}, & \text{if } \alpha = (j, i) \in \mathcal{A}, \\ -\infty, & \text{otherwise.} \end{cases}$$

Iteration ($p = 1, \dots, L - 1$): for $i = 1, \dots, n$ compute

$$a_{p+1}^{(i)}(t) = \mu \ln \left(\sum_{\alpha=(k,i) \in \mathcal{A}} e^{(a_p^{(k)}(t) - t^{(\alpha)})/\mu} \right),$$

Routes with bounded length

For the source j and length of the route p define the functions:

$$\left. \begin{aligned} a_p^{(i)}(t) &= \mu \ln g_{\mathcal{R}_{i,j}^p}(t/\mu) \\ b_p^{(i)}(t) &= \mu \ln g_{\widehat{\mathcal{R}}_{i,j}^p}(t/\mu) \end{aligned} \right\}, \quad i = 1, \dots, n,$$

Initialization: for $i = 1, \dots, n$ set

$$a_1^{(i)}(t) = b_1^{(i)}(t) = \begin{cases} -t^{(\alpha)}, & \text{if } \alpha = (j, i) \in \mathcal{A}, \\ -\infty, & \text{otherwise.} \end{cases}$$

Iteration ($p = 1, \dots, L - 1$): for $i = 1, \dots, n$ compute

$$\begin{aligned} a_{p+1}^{(i)}(t) &= \mu \ln \left(\sum_{\alpha=(k,i) \in \mathcal{A}} e^{(a_p^{(k)}(t) - t^{(\alpha)})/\mu} \right), \\ b_{p+1}^{(i)}(t) &= \mu \ln \left(e^{a_{p+1}^{(i)}(t)/\mu} + e^{b_p^{(i)}(t)/\mu} \right). \end{aligned}$$

Routes with bounded length

For the source j and length of the route p define the functions:

$$\left. \begin{aligned} a_p^{(i)}(t) &= \mu \ln g_{\mathcal{R}_{i,j}^p}(t/\mu) \\ b_p^{(i)}(t) &= \mu \ln g_{\widehat{\mathcal{R}}_{i,j}^p}(t/\mu) \end{aligned} \right\}, \quad i = 1, \dots, n,$$

Initialization: for $i = 1, \dots, n$ set

$$a_1^{(i)}(t) = b_1^{(i)}(t) = \begin{cases} -t^{(\alpha)}, & \text{if } \alpha = (j, i) \in \mathcal{A}, \\ -\infty, & \text{otherwise.} \end{cases}$$

Iteration ($p = 1, \dots, L - 1$): for $i = 1, \dots, n$ compute

$$\begin{aligned} a_{p+1}^{(i)}(t) &= \mu \ln \left(\sum_{\alpha=(k,i) \in \mathcal{A}} e^{(a_p^{(k)}(t) - t^{(\alpha)})/\mu} \right), \\ b_{p+1}^{(i)}(t) &= \mu \ln \left(e^{a_{p+1}^{(i)}(t)/\mu} + e^{b_p^{(i)}(t)/\mu} \right). \end{aligned}$$

Complexity: $O(m)$ operations per iteration,

Routes with bounded length

For the source j and length of the route p define the functions:

$$\left. \begin{aligned} a_p^{(i)}(t) &= \mu \ln g_{\mathcal{R}_{i,j}^p}(t/\mu) \\ b_p^{(i)}(t) &= \mu \ln g_{\widehat{\mathcal{R}}_{i,j}^p}(t/\mu) \end{aligned} \right\}, \quad i = 1, \dots, n,$$

Initialization: for $i = 1, \dots, n$ set

$$a_1^{(i)}(t) = b_1^{(i)}(t) = \begin{cases} -t^{(\alpha)}, & \text{if } \alpha = (j, i) \in \mathcal{A}, \\ -\infty, & \text{otherwise.} \end{cases}$$

Iteration ($p = 1, \dots, L - 1$): for $i = 1, \dots, n$ compute

$$\begin{aligned} a_{p+1}^{(i)}(t) &= \mu \ln \left(\sum_{\alpha=(k,i) \in \mathcal{A}} e^{(a_p^{(k)}(t) - t^{(\alpha)})/\mu} \right), \\ b_{p+1}^{(i)}(t) &= \mu \ln \left(e^{a_{p+1}^{(i)}(t)/\mu} + e^{b_p^{(i)}(t)/\mu} \right). \end{aligned}$$

Complexity: $O(m)$ operations per iteration, $O(mL)$ in total.

Routes with bounded length

For the source j and length of the route p define the functions:

$$\left. \begin{aligned} a_p^{(i)}(t) &= \mu \ln g_{\mathcal{R}_{i,j}^p}(t/\mu) \\ b_p^{(i)}(t) &= \mu \ln g_{\widehat{\mathcal{R}}_{i,j}^p}(t/\mu) \end{aligned} \right\}, \quad i = 1, \dots, n,$$

Initialization: for $i = 1, \dots, n$ set

$$a_1^{(i)}(t) = b_1^{(i)}(t) = \begin{cases} -t^{(\alpha)}, & \text{if } \alpha = (j, i) \in \mathcal{A}, \\ -\infty, & \text{otherwise.} \end{cases}$$

Iteration ($p = 1, \dots, L - 1$): for $i = 1, \dots, n$ compute

$$\begin{aligned} a_{p+1}^{(i)}(t) &= \mu \ln \left(\sum_{\alpha=(k,i) \in \mathcal{A}} e^{(a_p^{(k)}(t) - t^{(\alpha)})/\mu} \right), \\ b_{p+1}^{(i)}(t) &= \mu \ln \left(e^{a_{p+1}^{(i)}(t)/\mu} + e^{b_p^{(i)}(t)/\mu} \right). \end{aligned}$$

Complexity: $O(m)$ operations per iteration, $O(mL)$ in total.

Gradient in t : same complexity by Fast Backward Differentiation.

Routes with bounded length

For the source j and length of the route p define the functions:

$$\left. \begin{aligned} a_p^{(i)}(t) &= \mu \ln g_{\mathcal{R}_{i,j}^p}(t/\mu) \\ b_p^{(i)}(t) &= \mu \ln g_{\widehat{\mathcal{R}}_{i,j}^p}(t/\mu) \end{aligned} \right\}, \quad i = 1, \dots, n,$$

Initialization: for $i = 1, \dots, n$ set

$$a_1^{(i)}(t) = b_1^{(i)}(t) = \begin{cases} -t^{(\alpha)}, & \text{if } \alpha = (j, i) \in \mathcal{A}, \\ -\infty, & \text{otherwise.} \end{cases}$$

Iteration ($p = 1, \dots, L - 1$): for $i = 1, \dots, n$ compute

$$\begin{aligned} a_{p+1}^{(i)}(t) &= \mu \ln \left(\sum_{\alpha=(k,i) \in \mathcal{A}} e^{(a_p^{(k)}(t) - t^{(\alpha)})/\mu} \right), \\ b_{p+1}^{(i)}(t) &= \mu \ln \left(e^{a_{p+1}^{(i)}(t)/\mu} + e^{b_p^{(i)}(t)/\mu} \right). \end{aligned}$$

Complexity: $O(m)$ operations per iteration, $O(mL)$ in total.

Gradient in t : same complexity by Fast Backward Differentiation.

Limiting case ($\mu \rightarrow 0$): shortest path scheme

Routes with bounded length

For the source j and length of the route p define the functions:

$$\left. \begin{aligned} a_p^{(i)}(t) &= \mu \ln g_{\mathcal{R}_{i,j}^p}(t/\mu) \\ b_p^{(i)}(t) &= \mu \ln g_{\widehat{\mathcal{R}}_{i,j}^p}(t/\mu) \end{aligned} \right\}, \quad i = 1, \dots, n,$$

Initialization: for $i = 1, \dots, n$ set

$$a_1^{(i)}(t) = b_1^{(i)}(t) = \begin{cases} -t^{(\alpha)}, & \text{if } \alpha = (j, i) \in \mathcal{A}, \\ -\infty, & \text{otherwise.} \end{cases}$$

Iteration ($p = 1, \dots, L - 1$): for $i = 1, \dots, n$ compute

$$\begin{aligned} a_{p+1}^{(i)}(t) &= \mu \ln \left(\sum_{\alpha=(k,i) \in \mathcal{A}} e^{(a_p^{(k)}(t) - t^{(\alpha)})/\mu} \right), \\ b_{p+1}^{(i)}(t) &= \mu \ln \left(e^{a_{p+1}^{(i)}(t)/\mu} + e^{b_p^{(i)}(t)/\mu} \right). \end{aligned}$$

Complexity: $O(m)$ operations per iteration, $O(mL)$ in total.

Gradient in t : same complexity by Fast Backward Differentiation.

Limiting case ($\mu \rightarrow 0$): shortest path scheme (Ford-Fulkerson).

Stochastic route choice model

Stochastic route choice model

Let \mathcal{R} be the set of routes from node p to node k .

Stochastic route choice model

Let \mathcal{R} be the set of routes from node p to node k .
For $r \in \mathcal{R}$, the probability $p_r(t)$ to choose this route is

$$p_r(t) = e^{-c_r(t)/\mu} / \sum_{q \in \mathcal{R}} e^{-c_q(t)/\mu}.$$

Stochastic route choice model

Let \mathcal{R} be the set of routes from node p to node k .

For $r \in \mathcal{R}$, the probability $p_r(t)$ to choose this route is

$$p_r(t) = e^{-c_r(t)/\mu} / \sum_{q \in \mathcal{R}} e^{-c_q(t)/\mu}.$$

For a demand flow d , the *expected arc flow vector* is

$$f(t) = d \sum_{r \in \mathcal{R}} p_r(t) a_r.$$

Stochastic route choice model

Let \mathcal{R} be the set of routes from node p to node k .

For $r \in \mathcal{R}$, the probability $p_r(t)$ to choose this route is

$$p_r(t) = e^{-c_r(t)/\mu} / \sum_{q \in \mathcal{R}} e^{-c_q(t)/\mu}.$$

For a demand flow d , the *expected arc flow vector* is

$$f(t) = d \sum_{r \in \mathcal{R}} p_r(t) a_r.$$

Let us introduce the potential $\psi_{\mathcal{R}}(t) = \ln \sum_{r \in \mathcal{R}} e^{-c_r(t)}$.

Stochastic route choice model

Let \mathcal{R} be the set of routes from node p to node k .

For $r \in \mathcal{R}$, the probability $p_r(t)$ to choose this route is

$$p_r(t) = e^{-c_r(t)/\mu} / \sum_{q \in \mathcal{R}} e^{-c_q(t)/\mu}.$$

For a demand flow d , the *expected arc flow vector* is

$$f(t) = d \sum_{r \in \mathcal{R}} p_r(t) a_r.$$

Let us introduce the potential $\psi_{\mathcal{R}}(t) = \ln \sum_{r \in \mathcal{R}} e^{-c_r(t)}$.

Lemma.

Stochastic route choice model

Let \mathcal{R} be the set of routes from node p to node k .

For $r \in \mathcal{R}$, the probability $p_r(t)$ to choose this route is

$$p_r(t) = e^{-c_r(t)/\mu} / \sum_{q \in \mathcal{R}} e^{-c_q(t)/\mu}.$$

For a demand flow d , the *expected arc flow vector* is

$$f(t) = d \sum_{r \in \mathcal{R}} p_r(t) a_r.$$

Let us introduce the potential $\psi_{\mathcal{R}}(t) = \ln \sum_{r \in \mathcal{R}} e^{-c_r(t)}$.

Lemma. If $t/\mu \in \text{dom } \Psi_{\mathcal{R}}$, then $f(t) = -d \nabla \psi_{\mathcal{R}}(t/\mu)$.

Stochastic route choice model

Let \mathcal{R} be the set of routes from node p to node k .

For $r \in \mathcal{R}$, the probability $p_r(t)$ to choose this route is

$$p_r(t) = e^{-c_r(t)/\mu} / \sum_{q \in \mathcal{R}} e^{-c_q(t)/\mu}.$$

For a demand flow d , the *expected arc flow vector* is

$$f(t) = d \sum_{r \in \mathcal{R}} p_r(t) a_r.$$

Let us introduce the potential $\psi_{\mathcal{R}}(t) = \ln \sum_{r \in \mathcal{R}} e^{-c_r(t)}$.

Lemma. If $t/\mu \in \text{dom } \Psi_{\mathcal{R}}$, then $f(t) = -d \nabla \psi_{\mathcal{R}}(t/\mu)$.
This flow is feasible.

Stochastic route choice model

Let \mathcal{R} be the set of routes from node p to node k .

For $r \in \mathcal{R}$, the probability $p_r(t)$ to choose this route is

$$p_r(t) = e^{-c_r(t)/\mu} / \sum_{q \in \mathcal{R}} e^{-c_q(t)/\mu}.$$

For a demand flow d , the *expected arc flow vector* is

$$f(t) = d \sum_{r \in \mathcal{R}} p_r(t) a_r.$$

Let us introduce the potential $\psi_{\mathcal{R}}(t) = \ln \sum_{r \in \mathcal{R}} e^{-c_r(t)}$.

Lemma. If $t/\mu \in \text{dom } \Psi_{\mathcal{R}}$, then $f(t) = -d \nabla \psi_{\mathcal{R}}(t/\mu)$.
This flow is feasible.

Interesting sets; $\widehat{\mathcal{R}}_{p,k}^L$, $\widetilde{\mathcal{R}}_{p,k}$.

Stochastic traffic assignment

Stochastic traffic assignment

Network model: $\mathcal{N} = (\mathcal{V}, \mathcal{A})$.

Stochastic traffic assignment

Network model: $\mathcal{N} = (\mathcal{V}, \mathcal{A})$. For each arc α ,

Stochastic traffic assignment

- Network model:** $\mathcal{N} = (\mathcal{V}, \mathcal{A})$. For each arc α ,
- the travel time satisfies $t^{(\alpha)} \geq \bar{t}^{(\alpha)}$,

Stochastic traffic assignment

Network model: $\mathcal{N} = (\mathcal{V}, \mathcal{A})$. For each arc α ,

- the travel time satisfies $t^{(\alpha)} \geq \bar{t}^{(\alpha)}$,
- the arc flow satisfied $0 \leq f^{(\alpha)} \leq \bar{f}^{(\alpha)}$.

Stochastic traffic assignment

Network model: $\mathcal{N} = (\mathcal{V}, \mathcal{A})$. For each arc α ,

- the travel time satisfies $t^{(\alpha)} \geq \bar{t}^{(\alpha)}$,
- the arc flow satisfied $0 \leq f^{(\alpha)} \leq \bar{f}^{(\alpha)}$.

Performance:

Stochastic traffic assignment

Network model: $\mathcal{N} = (\mathcal{V}, \mathcal{A})$. For each arc α ,

- the travel time satisfies $t^{(\alpha)} \geq \bar{t}^{(\alpha)}$,
- the arc flow satisfied $0 \leq f^{(\alpha)} \leq \bar{f}^{(\alpha)}$.

Performance: If $f^{(\alpha)} < \bar{f}^{(\alpha)}$, then $t^{(\alpha)} = \bar{t}^{(\alpha)}$ (*Stable Dynamics*).

Stochastic traffic assignment

Network model: $\mathcal{N} = (\mathcal{V}, \mathcal{A})$. For each arc α ,

- the travel time satisfies $t^{(\alpha)} \geq \bar{t}^{(\alpha)}$,
- the arc flow satisfied $0 \leq f^{(\alpha)} \leq \bar{f}^{(\alpha)}$.

Performance: If $f^{(\alpha)} < \bar{f}^{(\alpha)}$, then $t^{(\alpha)} = \bar{t}^{(\alpha)}$ (*Stable Dynamics*).

Loading: Origin-destination flow data \mathcal{OD} .

Stochastic traffic assignment

Network model: $\mathcal{N} = (\mathcal{V}, \mathcal{A})$. For each arc α ,

- the travel time satisfies $t^{(\alpha)} \geq \bar{t}^{(\alpha)}$,
- the arc flow satisfied $0 \leq f^{(\alpha)} \leq \bar{f}^{(\alpha)}$.

Performance: If $f^{(\alpha)} < \bar{f}^{(\alpha)}$, then $t^{(\alpha)} = \bar{t}^{(\alpha)}$ (*Stable Dynamics*).

Loading: Origin-destination flow data \mathcal{OD} .

Equilibrium: Drivers choose paths in accordance to Logit Model.

Stochastic traffic assignment

Network model: $\mathcal{N} = (\mathcal{V}, \mathcal{A})$. For each arc α ,

- the travel time satisfies $t^{(\alpha)} \geq \bar{t}^{(\alpha)}$,
- the arc flow satisfied $0 \leq f^{(\alpha)} \leq \bar{f}^{(\alpha)}$.

Performance: If $f^{(\alpha)} < \bar{f}^{(\alpha)}$, then $t^{(\alpha)} = \bar{t}^{(\alpha)}$ (*Stable Dynamics*).

Loading: Origin-destination flow data \mathcal{OD} .

Equilibrium: Drivers choose paths in accordance to Logit Model.

Optimization problem: $\min_{t \geq \bar{t}} (\langle \bar{f}, t \rangle + \mu \psi(t/\mu))$, ($\mu > 0$)

where $\psi(t) = \sum_{(p,k) \in \mathcal{OD}} d_{p,k} \psi_{\mathcal{R}_{p,k}}(t)$.

Stochastic traffic assignment

Network model: $\mathcal{N} = (\mathcal{V}, \mathcal{A})$. For each arc α ,

- the travel time satisfies $t^{(\alpha)} \geq \bar{t}^{(\alpha)}$,
- the arc flow satisfied $0 \leq f^{(\alpha)} \leq \bar{f}^{(\alpha)}$.

Performance: If $f^{(\alpha)} < \bar{f}^{(\alpha)}$, then $t^{(\alpha)} = \bar{t}^{(\alpha)}$ (*Stable Dynamics*).

Loading: Origin-destination flow data \mathcal{OD} .

Equilibrium: Drivers choose paths in accordance to Logit Model.

Optimization problem:
$$\min_{t \geq \bar{t}} (\langle \bar{f}, t \rangle + \mu \psi(t/\mu)), \quad (\mu > 0)$$

where $\psi(t) = \sum_{(p,k) \in \mathcal{OD}} d_{p,k} \psi_{\mathcal{R}_{p,k}}(t)$.

NB 1. For $\hat{\mathcal{R}}_{p,k}^L$ and $\tilde{\mathcal{R}}_{p,k}$ this function is computable.

Stochastic traffic assignment

Network model: $\mathcal{N} = (\mathcal{V}, \mathcal{A})$. For each arc α ,

- the travel time satisfies $t^{(\alpha)} \geq \bar{t}^{(\alpha)}$,
- the arc flow satisfied $0 \leq f^{(\alpha)} \leq \bar{f}^{(\alpha)}$.

Performance: If $f^{(\alpha)} < \bar{f}^{(\alpha)}$, then $t^{(\alpha)} = \bar{t}^{(\alpha)}$ (*Stable Dynamics*).

Loading: Origin-destination flow data \mathcal{OD} .

Equilibrium: Drivers choose paths in accordance to Logit Model.

Optimization problem:
$$\min_{t \geq \bar{t}} (\langle \bar{f}, t \rangle + \mu \psi(t/\mu)), \quad (\mu > 0)$$

where $\psi(t) = \sum_{(p,k) \in \mathcal{OD}} d_{p,k} \psi_{\mathcal{R}_{p,k}}(t)$.

NB 1. For $\hat{\mathcal{R}}_{p,k}^L$ and $\tilde{\mathcal{R}}_{p,k}$ this function is computable.

2. The equilibrium flow is $f_{p,k}^* = -d_{p,k} \nabla \psi_{\mathcal{R}_{p,k}}(t^*/\mu)$, where $t^* \in R^m$ is the equilibrium time.

Incomplete information

Incomplete information

Data: $\mathcal{OD} = \mathcal{O} \times \mathcal{D}$,

Incomplete information

Data: $\mathcal{OD} = \mathcal{O} \times \mathcal{D}$,

- Weights $P^{(i)}$, reflecting the population for $i \in \mathcal{O}$,

Incomplete information

Data: $\mathcal{OD} = \mathcal{O} \times \mathcal{D}$,

- Weights $P^{(i)}$, reflecting the population for $i \in \mathcal{O}$,
- Weights $Q^{(j)}$, reflecting the number of jobs for $j \in \mathcal{D}$.

Incomplete information

Data: $\mathcal{OD} = \mathcal{O} \times \mathcal{D}$,

- Weights $P^{(i)}$, reflecting the population for $i \in \mathcal{O}$,
- Weights $Q^{(j)}$, reflecting the number of jobs for $j \in \mathcal{D}$.

Denote by Φ the total OD-flow.

Incomplete information

Data: $\mathcal{OD} = \mathcal{O} \times \mathcal{D}$,

- Weights $P^{(i)}$, reflecting the population for $i \in \mathcal{O}$,
- Weights $Q^{(j)}$, reflecting the number of jobs for $j \in \mathcal{D}$.

Denote by Φ the total OD-flow.

Expected minimal cost: $\theta_{\mathcal{R}_{p,k}}(t) = -\mu\psi_{\mathcal{R}_{p,k}}(t/\mu)$ (by Logit).

Incomplete information

Data: $\mathcal{OD} = \mathcal{O} \times \mathcal{D}$,

- Weights $P^{(i)}$, reflecting the population for $i \in \mathcal{O}$,
- Weights $Q^{(j)}$, reflecting the number of jobs for $j \in \mathcal{D}$.

Denote by Φ the total OD-flow.

Expected minimal cost: $\theta_{\mathcal{R}_{p,k}}(t) = -\mu \psi_{\mathcal{R}_{p,k}}(t/\mu)$ (by Logit).

Probability of link $i \rightarrow k$:
$$\pi_{i,k}(t) = \frac{P^{(i)} Q^{(k)} e^{-\theta_{\mathcal{R}_{i,k}}(t)/\mu}}{\sum_{(\ell,j) \in \mathcal{OD}} P^{(\ell)} Q^{(j)} e^{-\theta_{\mathcal{R}_{\ell,j}}(t)/\mu}}.$$

Incomplete information

Data: $\mathcal{OD} = \mathcal{O} \times \mathcal{D}$,

- Weights $P^{(i)}$, reflecting the population for $i \in \mathcal{O}$,
- Weights $Q^{(j)}$, reflecting the number of jobs for $j \in \mathcal{D}$.

Denote by Φ the total OD-flow.

Expected minimal cost: $\theta_{\mathcal{R}_{p,k}}(t) = -\mu\psi_{\mathcal{R}_{p,k}}(t/\mu)$ (by Logit).

Probability of link $i \rightarrow k$:
$$\pi_{i,k}(t) = \frac{P^{(i)}Q^{(k)}e^{-\theta_{\mathcal{R}_{i,k}}(t)/\mu}}{\sum_{(\ell,j) \in \mathcal{OD}} P^{(\ell)}Q^{(j)}e^{-\theta_{\mathcal{R}_{\ell,j}}(t)/\mu}}.$$

Expected ($i \rightarrow k$) arc flow: $-\Phi \cdot \pi_{i,k}(t) \nabla \psi_{\mathcal{R}_{i,k}}(t/\mu)$.

Incomplete information

Data: $\mathcal{OD} = \mathcal{O} \times \mathcal{D}$,

- Weights $P^{(i)}$, reflecting the population for $i \in \mathcal{O}$,
- Weights $Q^{(j)}$, reflecting the number of jobs for $j \in \mathcal{D}$.

Denote by Φ the total OD-flow.

Expected minimal cost: $\theta_{\mathcal{R}_{p,k}}(t) = -\mu\psi_{\mathcal{R}_{p,k}}(t/\mu)$ (by Logit).

Probability of link $i \rightarrow k$:
$$\pi_{i,k}(t) = \frac{P^{(i)}Q^{(k)}e^{-\theta_{\mathcal{R}_{i,k}}(t/\mu)}}{\sum_{(\ell,j) \in \mathcal{OD}} P^{(\ell)}Q^{(j)}e^{-\theta_{\mathcal{R}_{\ell,j}}(t/\mu)}}.$$

Expected ($i \rightarrow k$) arc flow: $-\Phi \cdot \pi_{i,k}(t) \nabla \psi_{\mathcal{R}_{i,k}}(t/\mu)$.

Optimization problem:
$$\min_{t \geq \bar{t}} [\langle \bar{f}, t \rangle + \Phi \cdot \mu\psi(t/\mu)],$$

where $\psi(t) = \ln \left(\sum_{i \in \mathcal{O}} \sum_{j \in \mathcal{D}} P^{(i)}Q^{(j)}g_{\mathcal{R}_{i,j}}(t) \right)$.

Incomplete information

Data: $\mathcal{OD} = \mathcal{O} \times \mathcal{D}$,

- Weights $P^{(i)}$, reflecting the population for $i \in \mathcal{O}$,
- Weights $Q^{(j)}$, reflecting the number of jobs for $j \in \mathcal{D}$.

Denote by Φ the total OD-flow.

Expected minimal cost: $\theta_{\mathcal{R}_{p,k}}(t) = -\mu\psi_{\mathcal{R}_{p,k}}(t/\mu)$ (by Logit).

Probability of link $i \rightarrow k$:
$$\pi_{i,k}(t) = \frac{P^{(i)}Q^{(k)}e^{-\theta_{\mathcal{R}_{i,k}}(t)/\mu}}{\sum_{(\ell,j) \in \mathcal{OD}} P^{(\ell)}Q^{(j)}e^{-\theta_{\mathcal{R}_{\ell,j}}(t)/\mu}}.$$

Expected ($i \rightarrow k$) arc flow: $-\Phi \cdot \pi_{i,k}(t) \nabla \psi_{\mathcal{R}_{i,k}}(t/\mu)$.

Optimization problem:
$$\min_{t \geq \bar{t}} [\langle \bar{f}, t \rangle + \Phi \cdot \mu\psi(t/\mu)],$$

where $\psi(t) = \ln \left(\sum_{i \in \mathcal{O}} \sum_{j \in \mathcal{D}} P^{(i)}Q^{(j)}g_{\mathcal{R}_{i,j}}(t) \right)$.

Expected OD-flows: can be computed by the gradients.

Conclusion

Conclusion

1. Stochastic equilibrium can be computed as a solution of a smooth convex minimization problem.

Conclusion

1. Stochastic equilibrium can be computed as a solution of a smooth convex minimization problem.
2. Stochastic model is more adequate.

Conclusion

1. Stochastic equilibrium can be computed as a solution of a smooth convex minimization problem.
2. Stochastic model is more adequate.
3. **Important aspects.**

Conclusion

1. Stochastic equilibrium can be computed as a solution of a smooth convex minimization problem.
2. Stochastic model is more adequate.
3. **Important aspects.**
 - Choice of μ ?

Conclusion

1. Stochastic equilibrium can be computed as a solution of a smooth convex minimization problem.
2. Stochastic model is more adequate.
3. **Important aspects.**
 - Choice of μ ? We need to ensure that \bar{t} is feasible:

$$\rho(E(\bar{t}/\mu)) < 1.$$

Conclusion

1. Stochastic equilibrium can be computed as a solution of a smooth convex minimization problem.
2. Stochastic model is more adequate.
3. **Important aspects.**
 - Choice of μ ? We need to ensure that \bar{t} is feasible:
$$\rho(E(\bar{t}/\mu)) < 1.$$
 - Choice of the optimization method? Characteristics of the problem?

Conclusion

1. Stochastic equilibrium can be computed as a solution of a smooth convex minimization problem.
2. Stochastic model is more adequate.
3. **Important aspects.**
 - Choice of μ ? We need to ensure that \bar{t} is feasible:
$$\rho(E(\bar{t}/\mu)) < 1.$$
 - Choice of the optimization method? Characteristics of the problem?
(New possibility: Universal Gradient Methods.)

Conclusion

1. Stochastic equilibrium can be computed as a solution of a smooth convex minimization problem.
2. Stochastic model is more adequate.
3. **Important aspects.**
 - Choice of μ ? We need to ensure that \bar{t} is feasible:
$$\rho(E(\bar{t}/\mu)) < 1.$$
 - Choice of the optimization method? Characteristics of the problem?
(New possibility: Universal Gradient Methods.)
4. **Open questions.**

Conclusion

1. Stochastic equilibrium can be computed as a solution of a smooth convex minimization problem.

2. Stochastic model is more adequate.

3. **Important aspects.**

- Choice of μ ? We need to ensure that \bar{t} is feasible:

$$\rho(E(\bar{t}/\mu)) < 1.$$

- Choice of the optimization method? Characteristics of the problem?

(New possibility: Universal Gradient Methods.)

4. **Open questions.**

- Interpretation of $\rho(E(t))$?

Conclusion

1. Stochastic equilibrium can be computed as a solution of a smooth convex minimization problem.

2. Stochastic model is more adequate.

3. **Important aspects.**

- Choice of μ ? We need to ensure that \bar{t} is feasible:

$$\rho(E(\bar{t}/\mu)) < 1.$$

- Choice of the optimization method? Characteristics of the problem?

(New possibility: Universal Gradient Methods.)

4. **Open questions.**

- Interpretation of $\rho(E(t))$?
- Network design (improve the structure, developments, long-run, etc.).

THANK YOU FOR YOUR ATTENTION!